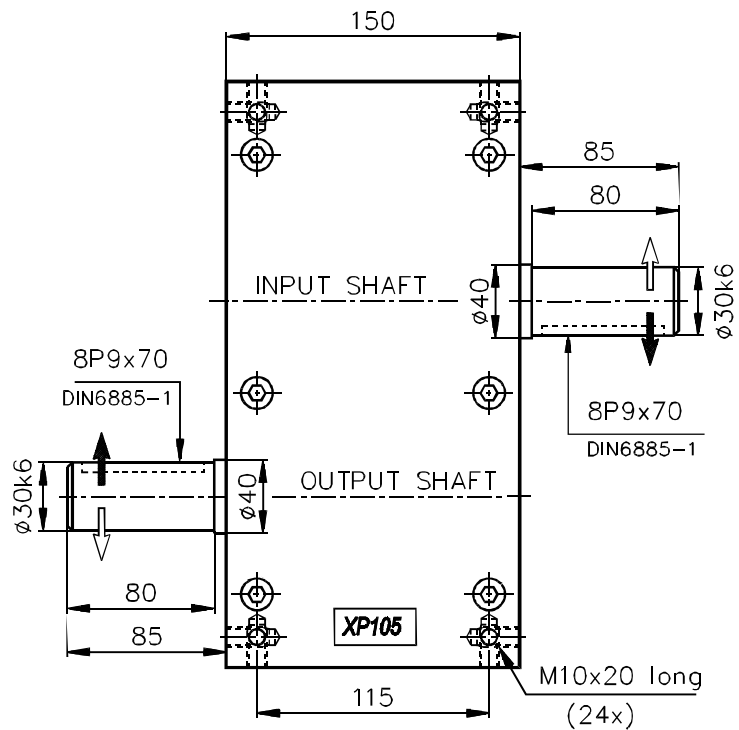


Center in shafts M10x22



General tolerances as per ISO 2768-m

Standard Indexer						
Number of stops n	Index angle α [°] from - to	Law of motion	Output torque at indexes/min [Nm]			Followers at pitch radius [mm]
			50	100	200	
1	300	mS 50	264	213	168	40
	330	mS 30	216	175	138	35
2	150	mS 50	254	204	155	35
	180-210	mS 30	297	240	191	40
	240-300	mS 0	280	227	183	40
3	120	mS 30	335	281	219	35
	150	mS 0	412	339	271	40
	180-300	mS 0	343	278	225	40
4	90	mS 0	292	284	221	35
	120-180	mS 0	328	291	234	40
	210-300	mS 0	309	251	203	40
5	120-180	mS 0	355	354	285	47
	210-300	mS 0	339	303	245	47
6*	150	mS 0	335	334	269	35
	180	mS 0	397	389	314	40
	210-300	mS 0	381	335	271	40
8*	120	mS 0	272	271	252	35
	150-180	mS 0	319	319	282	40
	210-300	mS 0	306	300	243	40
10*	150-300	mS 0	345	345	344	47
	210-300	mS 0	329	329	294	47

- Standard followers - $\phi 35$ mm.
- Housing made out of aluminium, weight approx. 32 kg.
- Internal moment of inertia $0,007 \text{ kgm}^2$.
- Torque during dwell approx. 20 % higher than permissible torque at 50 indexes/min.
- Keyways on input and output shafts positioned in the middle of a dwell.
- Keyways to DIN 6885/1.
- Reversibility of rotation possible.
- Long life lubrication.
- * Indexer with 6, 8 or 10 stops requires 2 revolutions per input shaft rotation.
- Drawings with detailed dimensions available on CAD (DXF, DWG).
- A full range of reducer, clutch and brake options, as well as output overloads, is available.
- A wide range of further number of stops, index angles, and motion laws including oscillating movements is available.
- All rights reserved for technical changes.